Influential Global and Local Contexts Guided Trace Representation for Fault Localization

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Trace data is critical for fault localization (FL) to analyze suspicious statements potentially responsible for a failure. However, existing trace representation meets its bottleneck mainly in two aspects: (1) the trace information of a statement is restricted to a local context (*i.e.*, a test case) without the consideration of a global context (*i.e.*, all test cases of a test suite); (2) it just uses the 'occurrence' for representation without strong FL semantics.

Thus, we propose UNITE: an infl<u>U</u>ential co<u>N</u>text-Gu<u>I</u>ded <u>T</u>race r<u>E</u>presentation, representing the trace from both global and local contexts with influential semantics for FL. UNITE embodies and implements two key ideas: (1) UNITE leverages the widely-used weighting capability from local and global contexts of information retrieval to reflect how important a statement (a word) is to a test case (a document) in all test cases of a test suite (a collection), where a test case (a document) and all test cases of a test suite (a collection) represent local and global contexts respectively; (2) UNITE further elaborates the trace representation from 'occurrence' (weak semantics) to 'influence' (strong semantics) by combing program dependencies. The large-scale experiments on 12 FL techniques and 20 programs show that UNITE significantly improves FL effectiveness.

CCS Concepts: • Software and its engineering \rightarrow Software testing and debugging.

Additional Key Words and Phrases: fault localization; trace representation; statement weighting; program dependence; suspiciousness;

1 INTRODUCTION

In software development and maintenance, debugging is one of the most expensive and time-consuming processes [18, 38, 48]. To reduce the cost, researchers have developed many fault localization (FL) techniques to provide automated assistance in seeking the faults that cause a failure [13, 23, 40, 52, 55, 57, 68].

Fig. 1 shows the typical process of FL. Suppose that we have a faulty program and a test suite for initialization. Then, FL executes the test suite on the program to collect and abstract the execution traces as a coverage matrix

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Fig. 1. The typical process of FL.

for trace representation, where an element denotes a statement *covered* (*i.e.*, the value of '1' denoting *occurrence*) or *not covered* (*i.e.*, the value of '0' representing *non-occurrence*) by a specific test case. Trace representation also constructs an error vector to represent the test results (*i.e.*, '1' for *fail* and '0' for *pass*). Next, FL takes as input the trace representation, and uses an evaluation model (*e.g.*, correlation coefficients [15, 16, 35, 39] and neural networks [53, 56, 65–67]) to evaluate the suspiciousness of each statement of being faulty. Finally, FL outputs the suspicious statements as a ranking list of all statements in descending order of suspiciousness.

Although trace representation is an indispensable component of the FL process, it still has some limitations. Existing trace representation uses the binary state of a statement (*i.e., occurrence* or *non-occurrence*) in a test case, which is restricted to a local context (*i.e.*, a test case) without the consideration of a global context (*i.e.*, all test cases of a test suite). For example, suppose that we have two statements s_1 and s_2 , where s_1 is only executed by the test case t_1 and s_2 is not only executed by t_1 but also executed by many other test cases. Considering the global context of a test suite, s_1 should be more important than s_2 for t_1 since s_1 only occurs in t_1 . For another example, suppose that we have two test cases t'_1 and t'_2 , where t'_1 executes 10 statements including the statement s'_1 and t'_2 covers 100 statements including s'_1 . Based on the global context of a test suite, s'_1 should be more important for t'_1 in comparison to t'_2 since t'_1 executes less statements than t'_2 . However, existing trace representation using binary state of a statement cannot capture such importance information. Therefore, its information is limited, *e.g.*, it cannot show to what degree of the importance of a statement is in an execution. Even if some approaches [11, 45] seek to enrich the representation from the local context of a test case itself, the lack of global context of all test cases of a test suite can cause some biases posing a negative effect on the effectiveness of fault localization [22], i.e., their representation actually performs worse than the widely-used binary trace representation [22]. Furthermore, existing trace representations mainly use the 'occurrence' semantics whereas the occurrence of a statement in a test case does not necessarily mean that the execution of the statement influences the program output. For example, suppose that a failing test case t_f executes two statements s_{f1} and s_{f2} , where the variable causing the faulty output of t_f is only computed by s_{f1} . In this case, we should exclude s_{f2} since its execution does not influence the faulty output. Nevertheless, the existing trace representation using statement coverage cannot capture such influence information. Thus, it lacks a strong FL semantics, restricting a deep analysis of suspicious evaluation model in evaluating the suspiciousness of a statement being faulty.

Therefore, this paper proposes UNITE: an inflUential co<u>N</u>text-Gu<u>I</u>ded <u>T</u>race r<u>E</u>presentation for effective FL, exploiting global and local contexts guided trace representation with influential semantics. Similar to the coverage matrix in Fig. 1, UNITE abstracts trace representation as a matrix by redefining the element which combines global and local contexts with influential semantics. Inspired by the widely-used word weighting capability from both local and global contexts of term frequency-inverse document frequency [41, 44] in information retrieval, UNITE applies this promising capability on trace representation in fault localization. Based on the term frequency-inverse document frequency, the idea of UNITE embodying the global and local contexts is that (1) if a statement is executed by many test cases, its weight should be lower for these test cases and the executed statements in these test cases have a small size, its weight should be higher for these test cases since the statement

is more important to these test cases. With the weights of a statement in all test cases of a test suite, UNITE can build linkages between the statement and the test results (*i.e.*, passing or failing) of test cases. To realize this idea, first, UNITE reformulates the trace information of a statement as the weight of a word in information retrieval. For an analogy, UNITE uses three sources of information for FL: a statement (a word), a test case (a document) and all test cases of a test suite (a collection). UNITE defines the trace representation of a statement as the weight of the statement (the word) by increasing proportionally to the number of times a statement (the word) occurs in the test case (the document), and being offset by the number of the test cases (the documents) in all test cases of a test suite (the collection) that contain the statement (the word), which helps to adjust for the fact that some statements (words) occur more frequently in general. Thus, UNITE elaborates **the local context** as **term frequency** that increases proportionally to the number of times a statement occurs in a test case (*i.e.*, **statement frequency**), and **the global context** as **inverse document frequency** that is offset by the number of the test case frequency).

Thus, UNITE elaborates **the local context** as **term frequency** that increases proportionally to the frequency of a statement occurs in a test case (*i.e.*, **statement frequency**), and **the global context** as **inverse document frequency** that is offset by the number of the test cases in all test cases of a test suite that contain the statement (*i.e.*, **inverse test case frequency**). Although UNITE considers trace representation from both local and global contexts, it still relies on the occurrence frequency of a statement or a test case. Therefore, UNITE further combines program dependencies into trace representation for upgrading the FL semantics. Specifically, UNITE uses program slicing [2, 47, 61] to identify those statements whose execution influences the incorrect output according to program dependencies. Then, UNITE updates higher weights of those statements with influential semantics, and thus upgrades the 'occurrence' (weak semantics) into the '**influence**' (strong semantics).

Since UNITE follows the widely-used matrix structure of most FL techniques, it means that UNITE may serve as a universal representation for most FL techniques. To evaluate the potential and the effectiveness of UNITE, we apply UNITE to 12 state-of-the-art FL techniques (*e.g.*, Dstar [54], CNN-FL [65], ProFL [28] and DeepRL4FL [26]) and conduct large-scale experiments on 20 benchmark programs. The results show that UNITE significantly improves FL effectiveness, *e.g.*, the average improvement for the important Top-N metric [17], *i.e.*, *Top-1*, *Top-3*, *Top-5* and *Top-10*, increases up to 2.19%, 11,18%, 11,47% and 14.18%, respectively.

The main contributions of this paper can be summarized as:

- We propose UNITE: an influential context-guided trace representation for FL by combining global and local contexts with influential semantics.
- We demonstrate the potential of UNITE as a universal representation for a wide spectrum of the state-ofthe-art FL techniques.
- We evaluate the effectiveness of UNITE across various 20 real-life large programs, showing that the UNITE is effective at improving FL.
- We open source the replication package online¹, including the source code, datasets and running examples.

The structure of the rest paper is organized as follows. Section 2 introduces related work. Section 3 depicts our approach UNITE. Section 4 and Section 5 present our large-scale experiments and the discussion. And Section 6 concludes the whole study and mentions future work.

2 RELATED WORK

This section surveys closely related work on fault localization (FL) from its two parts: **trace representation** and **suspiciousness evaluation**. More other work can be found in the survey [55].

¹https://github.com/oy-sarah/UNITE

2.1 Trace Representation

| Ν | staten | ients | е | rrors |
|------------------------|------------------------|-------|----------|-----------------------|
| x_{11} | x_{12} | | x_{1N} | $[e_1]$ |
| <i>x</i> ₂₁ | <i>x</i> ₂₂ | | x_{2N} | <i>e</i> ₂ |
| : | ÷ | •. | : | : |
| $ x_{M1} $ | x_{M2} | | x_{MN} | $\lfloor e_M \rfloor$ |

Fig. 2. FL Trace Representation on *M* test cases of a test suite.

FL usually defines a matrix (*i.e.*, a coverage matrix and an error vector) to represent the trace of each statement in each test case of a test suite and their corresponding test results. Next, FL takes as input the trace representation for its suspiciousness evaluation. The trace representation records the runtime information and test results of a test suite including the execution information of statements.

Fig. 2 shows the definition of the FL trace representation (*i.e.*, a $M \times (N + 1)$ matrix). Specifically, given a program P with N statements ($s_1, s_2, ..., s_N$), it is executed by a test suite T with M test cases ($t_1, t_2, ..., t_M$), which contain at least one failing test case (see Fig. 2). The element $x_{ij}=1$ means that the statement s_j occurs in (*i.e.*, is covered by) the test case t_i , and $x_{ij}=0$ otherwise. The $M \times N$ matrix records the execution information of each statement in the test suite T. The error vector e represents the test results. The element e_i equals to 1 if the test case t_i failed, and 0 otherwise. The error vector shows the test results of each test case (*i.e.*, failure or non-failure).

Even if some research [11, 45, 64, 69] tries to enrich trace representation of FL by using other information (*e.g.*, statement frequency), these approaches like the binary representation still have some limitations: (1) the trace information of a statement is restricted to a local context (*i.e.*, a test case) without the consideration of a global context (*i.e.*, all test cases of a test suite); (2) they just use the 'occurrence' for representation without strong FL semantics. Even worse, recent work [22] shows that these approaches (*e.g.*, [11, 45]) cause some bias posing a negative effect on fault localization effectiveness, *i.e.*, their elaboration on trace representation is not better than the binary state of FL trace representation. This motivates our work to solve the above two problems by proposing an FL trace representation to combine both local and global contexts and upgrade the 'occurrence' (weak semantics) into 'influence' (strong semantics).

2.2 Suspiciousness Evaluation

Based on the trace representation in Fig. 2, researchers develop many suspiciousness evaluation models to evaluate the suspiciousness of a statement of being faulty. We can roughly classify the suspiciousness evaluation models into two categories.

One category is suspiciousness evaluation using correlation coefficients, which are widely studied by the spectrum-based fault localization (SFL) researchers [15, 16, 35, 39]. Correlation coefficients are suspiciousness evaluation formulas, and SFL uses the trace representation to define four variables for the formulas as follows:

$$a_{np}(s_j) = \sum_{i \in np(s_j)} (1 - x_{ij}), \quad np(s_j) = \{i | (x_{ij} = 0) \land (e_i = 0)\}$$
(1)

$$a_{ep}(s_j) = \sum_{i \in ep(s_j)} x_{ij}, \ ep(s_j) = \{i | (x_{ij} > 0) \land (e_i = 0)\}$$
(2)

$$a_{nf}(s_j) = \sum_{i \in nf(s_j)} (1 - x_{ij}), \quad nf(s_j) = \{i | (x_{ij} = 0) \land (e_i = 1)\}$$
(3)

| | Name | Formulas | Name | Formulas |
|------|------------|--|--------|---|
| ER1' | Naish1 | $\begin{cases} -1 & if \ a_{ne} > 0 \\ a_{np} & if \ a_{ne} \le 0 \end{cases}$ | GP02 | $2\left(a_{ef} + \sqrt{a_{np}}\right) + \sqrt{a_{ep}}$ |
| | Optimal_P | $a_{ef} - \frac{a_{ep}}{a_{ep} + a_{np} + 1}$ | GP03 | $\sqrt{\left a_{ef}^2-\sqrt{a_{ep}} ight }$ |
| | GP13 | $a_{ef}\left(1+\frac{a_{ep}}{2a_{ep}+a_{ef}}\right)$ | GP19 | $a_{ef}\sqrt{\left a_{ep}-a_{ef}+a_{nf}-a_{np}\right }$ |
| | Wong1 | a _{ef} | Detar | a_{ef}^* |
| ER5 | Russel_Rao | $\frac{a_{ef}}{a_{ef} + a_{nf} + a_{ep} + a_{np}}$ | Dstai | $\overline{a_{nf}+a_{ep}}$ |
| | Binary | $\begin{cases} 0, if a_{ne} > 0 \\ 1, if a_{ne} \le 0 \end{cases}$ | Ochiai | $rac{a_{ef}}{\sqrt{(a_{ef}+a_{nf})(a_{ef}+a_{ep})}}$ |

Table 1. Suspiciousness evaluation using correlation coefficients.

$$a_{ef}(s_j) = \sum_{i \in ef(s_j)} x_{ij}, \ ef(s_j) = \{i | (x_{ij} > 0) \land (e_i = 1)\}$$

$$(4)$$

Eq. (1), Eq. (2), Eq. (3) and Eq. (4) show the computation of a_{np} , a_{nf} , a_{ep} , and a_{ef} for the statement *j* (*i.e.*, s_j), denoting the number of passing/failing test cases in which the statement was/wasn't executed. Based on the four variables for each statement (*i.e.*, a_{np} , a_{nf} , a_{ep} , and a_{ef}), SFL defines many suspiciousness evaluation formulas using correlation coefficients to evaluate the suspiciousness of each statement being faulty. Researchers have conducted both theoretical [59, 60] and empirical [39] analysis on finding the optimal SFL formulas using correlation coefficients, and identified seven effective ones, namely ER1', ER5, GP02, GP03, GP19, Ochiai and Dstar. Table 1 shows all the seven effective suspiciousness evaluation formulas using correlation coefficients'. Based on these formulas, some researchers incorporate more useful information into suspiciousness evaluation, *e.g.*, the popular and promising approach ProFL [28] leverages repair information as feedback.

The other one category is suspiciousness evaluation using neural networks, which are recently studied by the deep learning-based fault localization (DLFL) researchers [25, 46, 66, 71]. Based on the trace representation, this category tries to utilize artificial neural network with hidden layers [9, 20, 24, 34, 49, 67] to learn a fault localization model reflecting the statistical coincidences between test results (*i.e.*, failing or passing) and the executions of the different statements of a program (*i.e.*, occurrence or non-occurrence). We will introduce four representative suspiciousness evaluation models used in our experiments, namely MLP-FL [70], CNN-FL [65], BiLSTM-FL [67] and DeepRL4FL [26].

Fig. 3 shows the architecture of suspiciousness evaluation of DLFL using neural networks: one input layer, deep learning components with several hidden connected layers, and one output layer. In the input layer, the coverage matrix and the error vector of FL trace representation in the Fig. 2 are used as the training samples and their corresponding labels, respectively. In other words, *h* rows of the matrix $M \times N$ and its corresponding error vector are used as an input, which are the coverage information of *h* test cases and their corresponding test results starting from the *i*-th row, where $i \in \{1,1+h,1+2h,...,1+(\lfloor M/h \rfloor+1)\times h\}$. In deep learning components with several hidden connected layers, MLP-FL, CNN-FL and BiLSTM-FL use multi-layer perceptron, convolutional neural network and bi-directional long short-term memory respectively. DeepRL4FL integrate these basic neural

²The * in D* formula is usually assigned to 2.



Fig. 3. Suspiciousness evaluation using neural networks.

networks using multiple dimensions of features. In the output layer, DLFL uses *Sigmoid* function [24] because values sent into a *Sigmoid* function will be 0 to 1. Each element in the result vector of the *Sigmoid* function has difference with the corresponding element of the target vector. Back propagation algorithm is used to fine-tune the parameters of the model, and the goal is to minimize the difference between training result *y* and error vector *e*. The network is trained iteratively. Finally, DLFL using neural networks learns a trained model reflecting the relationship between statement coverage and test results. With the trained model, DLFL evaluates the suspiciousness of each statement.

Our work focuses on developing an effective universal representation for these suspciousness evaluation models, and can be widely used by these models.

3 APPROACH

3.1 Formulation

| | N stat | tements | errors | | N statements | 5 | ет | rrors |
|------------------------|------------------------|----------|-------------------|--------------------------|--------------------------|--------|--------------------------|-------------------------------------|
| $[x_{11}]$ | <i>x</i> ₁₂ | | x_{IN} | $GL_{influence}(x_{11})$ | $GL_{influence}(x_{12})$ | | $GL_{influence}(x_{1N})$ | $\begin{bmatrix} e_1 \end{bmatrix}$ |
| <i>x</i> ₂₁ | x ₂₂ | | $x_{2N} \mid e_2$ | $GL_{influence}(x_{21})$ | $GL_{influence}(x_{22})$ | | $GL_{influence}(x_{2N})$ | e ₂ |
| : | : | •. | : : | | : | • | : | : |
| $L_{X_{MI}}$ | x_{M2} | | $x_{MN}] [e_M]$ | $GL_{influence}(x_{M1})$ | $GL_{influence}(x_{M2})$ | | $GL_{influence}(x_{MN})$ | e_M |
| Orig | inal tra | ce repre | esentation | | UNITE represen | tation | | |

Fig. 4. The original FL trace representation and the UNITE representation of *M* test cases of a test suite.

First, we should formulate the problem. Given a program P with N statements $(s_1, s_2, ..., s_N)$, it is executed by M test cases $T(t_1, t_2, ..., t_M)$. Fig. 4 shows the original FL trace representation and the UNITE representation. let us recall the original FL trace representation (see the left matrix of Fig. 4). $x_{ij}=1$ indicates that the statement s_j occurs in the test case t_i , and 0 otherwise. The error vector e represents the test results. The element e_i equals to 1 if the test case t_i failed, and 0 otherwise. Since the original FL trace representation serves as a universal input for most FL techniques, UNITE will keep its structure for wide FL applicability. Thus, as shown in Fig. 4, the core work of UNITE is to redefine the elements of the original FL trace representation with influential global and local contexts.

3.2 UNITE with Global and Local Contexts

In the field of information retrieval, term frequency-inverse document frequency (TF-IDF) [41] is a popular word weighting technique designed to reflect the importance of a word to a document (*i.e.*, local context) in a collection (*i.e.*, global context). Inspired by the TF-IDF, UNITE utilizes its promising weighting capability by elaborating the trace representation to reflect the importance of a statement to a test case (*i.e.*, local context) in all test cases of a test suite (*i.e.*, global context). Thus, for an analogy, the basic idea of UNITE with global and local contexts can be roughly summarized as that if a statement (keyword) occurs only in a few test cases (documents), then it is easy to lock the FL target (search target), and the weight of the statement (word) should be relatively large. If a statement (word), and the weight of the statement (word) should be small. As a reminder, a statement occurring in a test case means that a statement is covered by the test case. Since UNITE considers the times of a statement itself will not affect UNITE.

To realize the above idea, UNITE defines **the local context** as the **term frequency** which increases proportionally to the frequency of a statement occurs in the test case (*i.e.*, **statement frequency**); and **the global context** as **inverse document frequency** which is offset by the number of the test cases in all test cases of a test suite that contain the statement (*i.e.*, **inverse test case frequency**). Specifically, UNITE defines the following TF_{local} , IDF_{global} , GL_{occur} as the local context, the global context and the combination of the global and local contexts, respectively.

$$TF_{local}\left(x_{ij}\right) = x_{ij} * \frac{1}{1 + log(N(t_i))}$$
(5)

$$IDF_{global}\left(x_{ij}\right) = log(\frac{M}{DF(s_i)}) \tag{6}$$

$$GL_{occur}(x_{ij}) = TF_{local}(x_{ij}) * IDF_{global}(x_{ij})$$
(7)

Based on the x_{ij} of the original FL trace representation (*i.e.*, the binary value of 1 or 0 of s_j in test case t_i), Eq. (5) calculates $TF_{local}(x_{ij})$, denoting the TF value of the statement s_j in the test case t_i (*i.e.*, **statement frequency** of s_j in test case t_i), where $N(t_i)$ means the number of executed statements in the test case t_i . Eq. (6) calculates $IDF_{global}(x_{ij})$, representing the IDF value of the statement s_j in the test suite (*i.e.*, **inverse document frequency** of s_j in the whole test suite), where $DF(s_j)$ indicates the number of test cases executing the statement s_j . In Eq. (5) and Eq. (6), we adopt the widely-used log function in TF-IDF. Eq. (7) calculates $GL_{occur}(x_{ij})$ via the the multiplication of $TF_{local}(x_{ij})$ and $IDF_{global}(x_{ij})$, denoting the TF-IDF value of the statement s_j in the test case t_i

Based on the Eq. (7), UNITE redefines an element of x_{ij} as $GL_{occur}(x_{ij})$ by combining the global and local contexts into trace representation.

3.3 UNITE with Influence Semantics

We can observe that the global and local contexts are constructed from statement coverage information. Although the statement coverage information is useful and effective, an occurrence of a statement in a test case does not necessarily mean that the execution of the statement will influence the output of the test case. For example, for a statement *stm*, its execution does not influence the incorrect output. Even if the statement *stm* has a high value of GL_{occur} , the statement *stm* should have the lowest weight because its execution is independent of the incorrect output. Thus, the new trace representation (*i.e.*, $GL_{occur}(x_{ij})$) still relies on the 'occurrence' semantics (*i.e.*, the occurrence frequency of a statement or a test case), and thus cannot capture such 'influence' semantics (*i.e.*, whether the execution of a statement influences the output or not). To further improve FL effectiveness, this motivates us to integrate 'influence' semantics into the trace representation via using program slicing [2, 61]

to capture whether the execution of a statement influences the output or not. Therefore, UNITE uses program slicing [2, 61] to elaborate the trace representation by upgrading the '**occurrence**' into the '**influence**' semantics.

Program slicing [2, 61] extracts the data and/or control dependencies of program statements to identify a subset of statements whose execution affects the output. It names the subset of statements as a slice. A slice is a program dependency graph showing how those statements influence the output according to data and/or control dependencies. Therefore, UNITE uses dynamic slicing [2, 61] on the output statement whose output value is incorrect to identify those statements affecting the faulty output value as an influential slice. Thus, an influential slice is defined as follows:

An influential slice: statements that directly or indirectly affect the computation of the faulty output value of a failure through chains of dynamic data and/or control dependencies.

For the computation of an influential slice, we use the following slicing criterion.

(8)

Where, *outStm* is an output statement whose value of a variable (*i.e., incorrectVar*) is incorrect in the execution of a failing test case (*i.e., failEx*). Dynamic slicing collects runtime information along the execution path of a test case, *i.e.*, the set of the executed statements of a test case. It means that a test case with a smaller set of executed statements is usually easier for a dynamic slicing tool to perform efficient instrumentation and produce compressed traces for space optimization. Thus, for multiple failing test cases, the one with the least executed statements usually is beneficial for the efficiency of constructing an influential slice. From the efficiency aspect, UNITE chooses the failing test case having the least executed statements to construct a slicing criterion in the Eq. (8), and inputs this slicing criterion into program slicing technique to construct an influential slice.

Based on the influential slice, UNITE defines Eq. (9) to combine influential semantics into trace representation.

$$GL_{influence}(x_{ij}) = GL_{occur}(x_{ij}) * SLICE(x_{ij})$$
(9)

Where, $SLICE(x_{ij}) = 1$ if the statement $s_j \in influentialSC$; and 0 otherwise. Eq. (9) assigns the lowest value to those statements not in the influential slice because their executions do not influence the faulty output.

Finally, as shown in Fig. 4, UNITE defines $GL_{influence}(x_{ij})$ to replace the original x_{ij} , and models a new trace representation (*i.e.*, a new matrix) with influential global and local contexts. FL techniques (*e.g.*, SFL and DLFL in Section 2) take as input the UNITE representation to analyze and evaluate the suspiciousness of a statement of being faulty.

3.4 An Illustrative Example

Fig. 5 shows an example illustrating how UNITE is applied. As shown in Fig. 5, we have a program P with a fault at the statement s_6 , and its function is to calculate the maximal value of three variables. The left six cells below each statement represent whether the statement is covered by the test case (1 for covered and 0 otherwise), evaluated by the original trace representation. The right six cells represent the $GL_{influence}$ values of each statement in each test case, evaluated by UNITE (see Eq. (9)). The rightmost cells below R indicate whether the test case is failing or not (1 for failing and 0 otherwise). In this illustrative example, we choose MLP-FL and ER5 as the representative for DLFL and SFL, which are described in Section 2. MLP-FL(UNITE) and ER5(UNITE) mean that MLP-FL and ER5 use the UNITE trace representation. UNITE uses the failing test case t_5 to calculate the influence slice. Here, we can observe that UNITE representation is more concise and precise than binary representation by purifying uninfluenctial statements and showing a magnitude of the importance of a statement in a test case.

After acquiring the trace representation, FL techniques take as input the representation to analyze and evaluate the suspiciousness of each statement of being faulty. For example, MLP-FL(UNITE) takes as input UNITE representation and its concrete process is as follows: first, UNITE constructs the MLP model with the number of input layer nodes being eight, three hidden layers with the number of each one's nodes being 10,

| | | | | Pro | gram I | o (max | imal va | alue of | <i>a,b,c</i>) | | | | | | | Bug | inform | ation | |
|--|---|--|-----------------------|-----------------------|----------|-------------------|-----------------------|------------------------|-----------------------|----------------|-----------------------|--------------------------------------|--------------------------------|---------------------------|-------|-------------------------------|--|-----------------------|---|
| $s_1:$ $s_2:$ $s_3:$ $s_4:$ $s_5:$ $s_6:$ | Read(a); Read(b); Read(c) ; if(c>a)and max = c;} else if (a< | d (c>b <b){< td=""><td>){</td><td></td><td>S- S-</td><td>7: max 8: else</td><td>c = a; $\{max\}$</td><td><i>z</i> = <i>b</i>;}</td><td></td><td>The in {s</td><td>fluent</td><td>ial slic 53, <i>s</i>4, <i>s</i></td><td>ce with 5, s₆}</td><td>n <i>t</i>₅:</td><td></td><td>s₆ Cor else</td><td>is faul rect fo e <i>if (a</i>></td><td>ty. rm: ∗b){</td><td></td></b){<> |){ | | S- S- | 7: max 8: else | c = a; $\{max\}$ | <i>z</i> = <i>b</i> ;} | | The in {s | fluent | ial slic 53, <i>s</i> 4, <i>s</i> | ce with 5, s ₆ } | n <i>t</i> ₅ : | | s ₆ Cor else | is faul rect fo e <i>if (a</i> > | ty. rm: ∗b){ | |
| Т | a,b,c | <i>s</i> ₁ | <i>s</i> ₂ | <i>s</i> ₃ | S_4 | s_5 | <i>s</i> ₆ | <i>S</i> ₇ | <i>s</i> ₈ | Т | <i>s</i> ₁ | <i>s</i> ₂ | <i>s</i> ₃ | S_4 | S_5 | <i>s</i> ₆ | <i>S</i> ₇ | <i>S</i> ₈ | R |
| t_1 | 1,2,3 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | t ₁ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| <i>t</i> ₂ | -2,-7,5 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | t ₂ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| t ₃ | 5,-6,-8 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 1 | t ₃ | 0 | 0 | 0 | 0 | 0.06 | 0 | 0 | 0 | 1 |
| t_4 | 5,4,3 | 1 | 1 | 1 | 1 | 0 | 1 | 0 | 1 | t ₄ | 0 | 0 | 0 | 0 | 0.06 | 0 | 0 | 0 | 1 |
| <i>t</i> ₅ | 4,7,1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | t ₅ | 0 | 0 | 0 | 0 | 0.06 | 0.17 | 0 | 0 | 1 |
| t ₆ | -1,2,1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 0 | t ₆ | 0 | 0 | 0 | 0 | 0.06 | 0.17 | 0 | 0 | 1 |
| MIDEL | value | 0.62 | 0.64 | 0.61 | 0.69 | 0.57 | 0.59 | 0.60 | 0.58 | MLP-FL | 0.56 | 0.28 | 0.19 | 0.46 | 0.79 | 0.95 | 0.97 | 0.88 | |
| MLP-FL | rank | 3 | 2 | 4 | 1 | 8 | <u>6</u> | 5 | 7 | (UNITE) | 5 | 7 | 8 | 6 | 4 | <u>2</u> | 1 | 3 | |
| ER5 | value | 0.67 | 0.67 | 0.67 | 0.67 | 0 | 0.67 | 0.33 | 0.33 | ER5 | 0 | 0 | 0 | 0 | 0 | 0.11 | 0.08 | 0 | |
| EKJ | rank | 1 | 2 | 3 | 4 | 8 | 5 | 6 | 7 | (UNITE) | 6 | 7 | 8 | 4 | 5 | 1 | 2 | 3 | |

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Fig. 5. An Example illustrating our approach.

and the number of output layer nodes being 1; then, we input the vector t_1 (0,0,0,0,0,0,0) and its result 0, then vector t_2 (0,0,0,0,0,0,0,0) and its result 0 into the input layer until all the vectors of UNITE representation are all inputted into the network. After that, we train the network iteratively to acquire the relationship between the execution influence of a statement and the test results. Thirdly, we construct the virtual test set which is an eight dimensional unit matrix, then put it into the network, and finally obtain the suspiciousness values. Based on these information, MLP-FL(UNITE) outputs a ranking list of all statements in descending order. The original MLP-FL uses the binary representation to perform a similar process to evaluate the suspiciousness of each statement of being faulty. The results show that the faulty statement s_6 is ranked 2nd by UNITE and ranked 6th by the original MLP-FL.

Based on the binary representation and UNITE representation, ER5 and ER5(UNITE) both output a ranking list of all statements in descending order. The results show that the faulty statement s_6 is ranked *1st* by UNITE and ranked *5th* by the original ER5 using the binary representation. It should be noted that when the statements have the same suspiciousness value, we adopt the widely strategy by ranking them in the ascending order of their line numbers. As shown in Fig. 5, although s_1 , s_2 , s_3 , s_4 and s_6 have the same highest suspiciousness value in ER5, s_6 is ranked 5th for its larger line number. Thus, for different strategies of breaking the tie, the ranks of those statements with the same suspiciousness value may be slightly different.

We can first observe that global and local contexts of UNITE work. Since the statements s_1 , s_2 , s_3 and s_4 are executed by all the 6 test cases, their GL_{occur} values are 0 in comparison to the other statements, and thus their $GL_{influence}$ are 0. Furthermore, the statement s_6 and s_7 acquire a decimal value, rather than a binary value, showing how important of a statement is in a test case. Then, the influence semantics of UNITE works. Due to using the influential slice, the execution of s_5 and s_8 do not influence the faulty output of t5, their *SLICE* values are 0 and thus their $GL_{influence}$ are 0 Thus, based on this illustrative example, we can observe that the two parts of UNITE (*i.e.*, global and local contexts, and influential semantics) both contribute to FL effectiveness,

leading to better FL effectiveness over the original trace representation. Section 4.3.2 offers an evaluation on the contribution of each part of UNITE to FL effectiveness.

4 EXPERIMENTS

4.1 Experimental Setup

| Program | Description | Versions | KLOC | Test | Туре |
|------------------|--------------------------------------|----------|------|-------|--------|
| python | General-purpose language | 8 | 407 | 355 | Real |
| gzip | Data compression | 5 | 491 | 12 | Real |
| libtiff | Image processing | 12 | 77 | 78 | Real |
| space | ADL interpreter | 35 | 6.1 | 13585 | Real |
| spoon | Java code analysis & transformation | 31 | 76 | 1114 | Real |
| dubbo | Apache incubator dubbo | 1 | 0.6 | 90 | Real |
| jackson-databind | General data binding | 13 | 99 | 1711 | Real |
| oak | Apache jackrabbit oak | 1 | 1.8 | 2403 | Real |
| debezium | Platform for change data capture | 4 | 53 | 508 | Real |
| byte-buddy | Runtime code generation for the JVM | 3 | 140 | 8066 | Real |
| AutomatedCar | Passenger vehicle behavior simulator | 1 | 2 | 48 | Real |
| cash-count | Accounting software back-end | 2 | 0.7 | 16 | Real |
| nanoxml_v1 | XML parser | 7 | 5.4 | 206 | Seeded |
| nanoxml_v2 | XML parser | 7 | 5.7 | 206 | Seeded |
| nanoxml_v3 | XML parser | 10 | 8.4 | 206 | Seeded |
| nanoxml_v5 | XML parser | 7 | 8.8 | 206 | Seeded |
| chart | JFreeChart | 26 | 96 | 2205 | Real |
| math | Apache commons math | 106 | 85 | 3602 | Real |
| lang | Apache commons-lang | 65 | 22 | 2245 | Real |
| time | Joda-Time | 27 | 53 | 4130 | Real |

Table 2. Subject programs.

Benchmarks The experiments choose the subject programs for the two reasons: (1) they are the widely used large-sized programs (*e.g.*, [24, 33, 35–37, 39, 42, 55, 65, 66]) in fault localization; (2) they are easy to be acquired for enabling comparable and reproducible studies. Table 2 summarizes the 20 subject programs. For each program, it provides a brief functional description (column 'Description'), the number of faulty versions used (column 'Versions'), the number of thousand lines of statements (column 'KLOC'), the number of test cases (column 'Test') and the type of the faults (column 'Type'). The first four programs are real faults, among which *python, gzip* and *libtiff* are collected from ManyBugs³, and *space* is acquired from the SIR⁴. The next seven programs are real faults from BEARS⁵. Then, the next four programs are seeded faults of the four sperate releases of *nanoxml* acquired from the SIR. The last four programs (*i.e., chart, math, lang* and *time*) are acquired from Defectcs4J⁶. As a reminder, since the recent studies [10, 71] have identified over-fitting benchmarks (*e.g.,* Defects4J) for FL, we use the recently recommended benchmarks [29] (*e.g.,* BEARS) to alleviate this problem. Therefore, we do not

³ManyBugs, https://repairbenchmarks.cs.umass.edu/ManyBugs/.

⁴SIR, http://sir.unl.edu/portal/index.php.

 $^{{}^{5}\}text{BEARS, https://github.com/bears-bugs/bears-benchmark.}$

⁶Defects4J, http://defects4j.org.

include the experimental results of Defects4J in Section 4.3 and provide a discussion on the effect of benchmarks over-fitting on our approach using Defects4J in Section 5.1.

We use JSlice⁷ and Javaslicer⁸ for slicing Java programs, and WET⁹ for slicing C Programs. Due to running environments, the tools cannot slice some faulty versions, and we remove these versions in our evaluation.

Baselines According to the extensive existing studies [23, 26, 28, 31, 32, 39, 43, 51, 59, 60, 65, 66], the experiments use the 12 state-of-the-art FL approaches as the baselines, *i.e.*, ER5, GP02, GP03, Dstar, ER1', GP19, Ochiai, MLP-FL, CNN-FL, BiLSTM-FL, ProFL and DeepRL4FL. We implement the 12 baselines including the parameters as described in their publications.

Environment The physical environment of the experiments is on a computer containing a CPU of Intel I5-2640 with 128G physical memory, and two 12G GPUs of NVIDIA TITAN X Pascal. The operating system is Ubuntu 16.04.3. We conducted the experiments on the MATLAB R2016b.

4.2 Evaluation Metrics

We adopt four widely used metrics to evaluate the effectiveness of UNITE, namely *Top-N accuracy* [17, 38], *Mean Average Rank (MAR)* [24], *Mean First Rank (MFR)* [24] and Relative Improvement (*RImp*) [4, 7, 21]. A higher value of *Top-N Accuracy* means better localization effectiveness, while a lower value denotes better localization effectiveness for the other four metrics.

Top-N Accuracy It denotes the percentage of faults located within the first *N* position of a ranked list of all statements in descending order of suspiciousness returned by a FL approach.

Mean Average Rank (MAR) It is the mean of the average rank of all faults using a FL approach.

Mean First Rank (MFR) For a fault with multiple faulty statements, locating the first one is critical since the others may be located after that. *MFR* is the mean of the first faulty statement's rank of all faults using a localization approach.

Relative Improvement (RImp) It is to compare the total number of statements that need to be examined to find all faults using UNITE versus the number that need to be examined by without using UNITE.

4.3 Experimental Results

4.3.1 RQ1. What is the FL effectiveness of UNITE compared with the original state-of-the-art FL baselines?

We compare 12 state-of-the-art FL baselines using UNITE with the original ones to answer RQ1.

Top-N Accuracy, MAR and MFR Parnin and Orso [38] conducted a user study of evaluating the usefulness of fault localization techniques in assisting developers, and recommended using the rank of the faulty statement to evaluate fault localization effectiveness. Since then, *Top-N, MAR* and *MFR* are widely used in fault localization. Afterwards many comprehensive user studies (*e.g.*, [17, 58]) show that it is useful to help developers in debugging by using these metrics. Thus, our experiments use *Top-N, MAR*, and *MFR* to compare the 12 baselines between using UNITE and using the original representation. Table 3 presents their distribution among 12 fault localization approaches using original trace representation and UNITE representation, respectively. As shown in Table 3, UNITE achieves promising best localization effectiveness in all 12 scenarios in comparison to the baselines without using UNITE. Take one FL technique ER5 as an example. UNITE shows an increase of 1.64%, 9.84%, 8.20% and 9.91% improvement over ER5 for the Top-1, Top-3, Top-5 and Top-10 metrics respectively. The *MAR* and *MFR* are 134 and 125 respectively, achieving (421-134)/421=68.17% and (263-125)/263=52.47% relative improvement over ER5 respectively.

⁷http://jslice.sourceforge.net/.

⁸https://github.com/hammacher/javaslicer/.

⁹http://wet.cs.ucr.edu/.

| Comparison | top-1 | top-3 | top-5 | top-10 | MAR | MFR |
|------------------|--------|---------|---------|---------|-----|-----|
| ĒR5 | 1.09% | 5.46% | 9.29% | 11.95% | 421 | 263 |
| ER5(UNITE) | +1.64% | +9.84% | +8.20% | +9.91% | 134 | 125 |
| GP02 | 1.09% | 6.01% | 8.20% | 11.29% | 464 | 289 |
| GP02(UNITE) | +2.19% | +8.74% | +11.47% | +11.66% | 124 | 111 |
| GP03 | 1.09% | 5.76% | 10.14% | 12.57% | 417 | 251 |
| GP03(UNITE) | +1.64% | +11.18% | +7.11% | +7.66% | 131 | 119 |
| Dstar | 2.73% | 6.56% | 14.27% | 23.50% | 386 | 243 |
| Dstar(UNITE) | +0.55% | +5.94% | +3.76% | +4.92% | 125 | 113 |
| ER1' | 2.73% | 5.21% | 7.10% | 11.29% | 425 | 317 |
| ER1'(UNITE) | +0.00% | +5.72% | +7.11% | +10.63% | 127 | 115 |
| GP19 | 2.73% | 6.56% | 12.57% | 13.11% | 417 | 278 |
| GP19(UNITE) | +0.55% | +6.98% | +6.18% | +10.39% | 126 | 121 |
| Ochiai | 2.73% | 6.56% | 13.70% | 19.13% | 397 | 227 |
| Ochiai(UNITE) | +0.55% | +9.29% | +4.01% | +7.1% | 122 | 112 |
| MLP-FL | 1.09% | 4.32% | 6.56% | 9.29% | 471 | 335 |
| MLP-FL(UNITE) | +1.10% | +7.16% | +8.19% | +11.48% | 137 | 129 |
| CNN-FL | 2.73% | 6.01% | 11.48% | 17.53% | 407 | 251 |
| CNN-FL(UNITE) | +0.55% | +10.93% | +6.55% | +3.78% | 123 | 117 |
| BiLSTM-FL | 1.09% | 3.28% | 6.15% | 8.74% | 493 | 354 |
| BiLSTM-FL(UNITE) | +1.10% | +7.65% | +8.06% | +14.18% | 133 | 124 |
| ProFL | 3.54% | 7.64% | 16.75% | 25.95% | 365 | 227 |
| ProFL(UNITE) | +0.78% | +9.85% | +6.75% | +4.1% | 122 | 107 |
| DeepRL4FL | 7.10% | 15.41% | 22.95% | 26.23% | 323 | 219 |
| DeepRL4FL(UNITE) | +0.00% | +4.81% | +3.83% | +6.56% | 103 | 96 |

Table 3. Top-N, MAR and MFR comparison of 13 FL approaches using UNITE over without using UNITE



Fig. 6. RImp comparison of 12 FL baselines using UNITE vs without using UNITE.

RImp distribution For a detailed improvement, we adopt *RImp* to evaluate UNITE. Fig. 6 shows the *RImp* distribution of UNITE: the *RImp* on the 12 FL baselines without using UNITE. As shown in Fig. 6, the *RImp* score is less than 100% in all approaches, meaning that UNITE improves localization effectiveness of all the 13

FL baselines. The statements that need to be examined decrease ranging from 14.10% in MLP-FL to 70.47% in DeepRL4FL. It also means that UNITE, obtains a maximum saving of 85.90% (100%-14.10%=85.90%) in MLP-FL and the minimum saving is 29.53% (100%-70.47%=48.68%) in DeepRL4FL, which indicates that UNITE can save from 29.53% to 85.90% of the number of statements examined among the fault localization approaches. Based on the *RImp* scores, we can observe that there is a significant saving after using UNITE, showing that UNITE is effective to improve fault localization.

Statistical comparison To investigate whether the difference between the baselines using UNITE and without using UNITE is statistically significant, we adopt Wilcoxon-Signed-Rank Test [5], with a Bonferroni correction [1], which is a non-parametric statistical hypothesis test for testing the differences between pairs of measurements F(x) and G(y). The experiments performed 12 paired Wilcoxon-Signed-Rank tests by using the *ranks* [30] of the faulty statements as the pairs of measurements F(x) and G(y). Each test uses left-tailed *p*-value checking at the σ level of 0.05. Specifically, we use the list of the *ranks* of the faulty statements using UNITE in all faulty versions of all programs as the list of measurements of F(x), while the list of measurements of G(y) is the list of the *ranks* of the faulty statements of G(y) is the list of the *ranks* of using UNITE in all faulty versions of all programs. If p<0.05, H_1 that the *ranks* of using UNITE has BETTER effectiveness than without using UNITE; otherwise, H_0 that *ranks* of using UNITE does not significantly tend to be smaller than that of without using UNITE is accepted, meaning that using UNITE does not perform better than without using UNITE.

Table 4 and Table 5 show the Wilcoxon-Signed-Rank Test results on this relationship, where the cells show the *p* values of Wilcoxon-Signed-Rank Tests. The results show that the *ranks* of the faulty statements of all the 12 FL approaches using UNITE are significantly smaller than those of all the 12 baselines using original trace representation in all programs, yielding BETTER results in all cases.

To further assess the difference quantitatively, we leverage the nonparametric Vargha-Delaney A-test, which is recommended in [3], to evaluate the magnitude of the difference by measuring effect size (scientific significance). For A-test, the bigger deviation of A-statistic is from the value of 0.5, the greater difference is between the two studied groups. Vargha and Delaney [50] suggest that A-test of greater than 0.64 (or less than 0.36) is indicative of "medium" effect size, and of greater than 0.71 (or less than 0.29) can be indicative of a promising "large" effect size.

Table 6 shows the A-Test results of 12 FL approaches using UNITE vs without using UNITE. We could observe that UNITE arrives at the promising "large" effect size, thus showing better performance. Therefore, it is statistically significant that UNITE outperforms FL without using UNITE.

Summary for RQ1 In RQ1, we explore the effectiveness of UNITE over original 12 FL baselines. We can safely conclude that the 12 techniques with UNITE significantly outperform the original ones, showing that incorporating influential global and local contexts guided trace representation into FL is potential to improve FL effectiveness.

4.3.2 RQ2. Does each part of UNITE contribute to FL effectiveness?

UNITE has two major parts: combining global and local contexts into representation and incorporating influential semantics into representation. It is desirable to see whether each part of UNITE contributes to FL effectiveness. Therefore, We implement UNITE with each part as UNITE(GLContexts) and UNITE(Influence), respectively. There are two cases: (1) we compare UNITE(GLContexts) and UNITE(Influence) with the original trace representation to check whether each part improves the original one; (2) we compare UNITE with each part (*i.e.*, UNITE(GLContexts) and UNITE(Influence)) to check whether UNITE successfully combines two parts to achieve better effectiveness than each part. We use the *ranks* of the faulty statements as measurements, and conduct Wilcoxon-Signed-Rank Test with a Bonferroni correction at the σ level of 0.05 for each comparison of the above two cases. Furthermore, for each comparison of the above two cases, we adopt the nonparametric Vargha-Delaney A-test to evaluate the magnitude of their difference by measuring effect size.

| Co | omparison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | Co | mparison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion |
|---------|------------------|----------|-----------------|----------------|------------|---------|------------------|----------|-----------------|----------------|------------|
| | gzip | 0.008 | 0.997 | 5.00e-04 | BETTER | | gzip | 0.027 | 0.899 | 0.018 | BETTER |
| | libtiff | 0.018 | 0.978 | 0.005 | BETTER | | libtiff | 0.011 | 0.969 | 0.009 | BETTER |
| | python | 0.010 | 0.958 | 0.012 | BETTER | | python | 0.018 | 0.963 | 0.003 | BETTER |
| | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER | | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER |
| | nanoxml_v1 | 0.017 | 0.929 | 0.010 | BETTER | | nanoxml_v1 | 0.045 | 0.707 | 0.048 | BETTER |
| | nanoxml_v2 | 0.018 | 0.963 | 0.019 | BETTER | | nanoxml_v2 | 0.039 | 0.789 | 0.041 | BETTER |
| | nanoxml_v3 | 0.008 | 0.989 | 0.003 | BETTER | 0744 | nanoxml_v3 | 0.46 | 0.705 | 0.039 | BETTER |
| ER5 | nanoxml_v5 | 0.013 | 0.985 | 0.007 | BETTER | GP02 | nanoxml_v5 | 0.009 | 0.985 | 3.01e-04 | BETTER |
| (UNITE) | spoon | 0.008 | 0.997 | 5.0e-04 | BETTER | (UNITE) | spoon | 0.011 | 0.995 | 6.43e-03 | BETTER |
| VS | dubbo | 0.008 | 0.997 | 0.003 | BETTER | VS | dubbo | 0.014 | 0.950 | 0.009 | BETTER |
| ER5 | jackson-databind | 0.013 | 0.929 | 0.009 | BETTER | GP02 | jackson-databind | 0.025 | 0.896 | 0.023 | BETTER |
| | oak | 0.018 | 0.963 | 0.009 | BETTER | | oak | 0.011 | 0.969 | 0.009 | BETTER |
| | debezium | 0.011 | 0.969 | 0.007 | BETTER | | debezium | 0.018 | 0.966 | 0.003 | BETTER |
| | byte-buddy | 0.012 | 0.989 | 0.003 | BETTER | | byte-buddy | 0.011 | 0.969 | 0.009 | BETTER |
| | AutomatedCar | 0.017 | 0.977 | 0.008 | BETTER | | AutomatedCar | 0.018 | 0.963 | 0.019 | BETTER |
| | cash-count | 0.013 | 0.981 | 0.009 | BETTER | | cash-count | 0.046 | 0.705 | 0.039 | BETTER |
| | total | 4.20e-12 | 1.000 | 2.15e-12 | BETTER | | total | 2.99e-09 | 1.000 | 1.53e-09 | BETTER |
| | gzip | 0.012 | 0.899 | 0.013 | BETTER | | gzip | 0.012 | 0.899 | 0.013 | BETTER |
| | libtiff | 0.011 | 0.969 | 0.009 | BETTER | | libtiff | 0.011 | 0.969 | 0.09 | BETTER |
| | python | 0.018 | 0.967 | 4.00e-04 | BETTER | | python | 0.018 | 0.963 | 3.00e-04 | BETTER |
| | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER | | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER |
| | nanoxml v1 | 0.045 | 0.707 | 0.046 | BETTER | | nanoxml v1 | 0.045 | 0.707 | 0.046 | BETTER |
| | nanoxml v2 | 0.011 | 0.969 | 0.009 | BETTER | | nanoxml v2 | 0.043 | 0.789 | 0.039 | BETTER |
| | nanoxml_v3 | 0.047 | 0.663 | 0.042 | BETTER | | nanoxml_v3 | 0.047 | 0.663 | 0.042 | BETTER |
| GP03 | nanoxml_v5 | 0.013 | 0.985 | 0.003 | BETTER | Dstar | nanoxml_v5 | 0.013 | 0.985 | 0.003 | BETTER |
| (UNITE) | spoon | 0.008 | 1.000 | 4.58e-04 | BETTER | (UNITE) | spoon | 0.008 | 0.962 | 0.007 | BETTER |
| vs | dubbo | 0.008 | 0.970 | 0.005 | BETTER | vs | dubbo | 0.045 | 0.728 | 0.041 | BETTER |
| GP03 | jackson-databind | 0.012 | 0.989 | 0.003 | BETTER | Dstar | jackson-databind | 0.024 | 0.896 | 0.035 | BETTER |
| | oak | 0.011 | 0.961 | 0.009 | BETTER | | oak | 0.015 | 0.909 | 0.010 | BETTER |
| | debezium | 0.018 | 0.963 | 0.003 | BETTER | | debezium | 0.007 | 0.985 | 0.003 | BETTER |
| | byte-buddy | 0.011 | 0.969 | 0.014 | BETTER | | byte-buddy | 0.045 | 0.707 | 0.048 | BETTER |
| | AutomatedCar | 0.011 | 0.969 | 0.009 | BETTER | | AutomatedCar | 0.018 | 0.963 | 0.003 | BETTER |
| | cash-count | 0.046 | 0.705 | 0.039 | BETTER | | cash-count | 0.047 | 0.663 | 0.042 | BETTER |
| | total | 2.32e-08 | 1.000 | 1.25e-08 | BETTER | | total | 1.61e-07 | 1.000 | 8.19e-08 | BETTER |
| | gzip | 0.017 | 0.899 | 0.016 | BETTER | | gzip | 0.008 | 0.978 | 0.007 | BETTER |
| | libtiff | 0.011 | 0.969 | 0.009 | BETTER | | libtiff | 0.11 | 0.969 | 0.009 | BETTER |
| | python | 0.018 | 0.963 | 0.003 | BETTER | | python | 0.018 | 0.963 | 0.003 | BETTER |
| | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER | | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER |
| | nanoxml v1 | 0.045 | 0.707 | 0.047 | BETTER | | nanoxml v1 | 0.011 | 0.966 | 0.011 | BETTER |
| | nanoxml v2 | 0.011 | 0.969 | 0.009 | BETTER | | nanoxml_v2 | 0.011 | 0.969 | 0.009 | BETTER |
| | nanoxml v3 | 0.045 | 0.663 | 0.042 | BETTER | | nanoxml v3 | 0.012 | 0.953 | 0.009 | BETTER |
| ER1' | nanoxml_v5 | 0.003 | 0.985 | 0.008 | BETTER | GP19 | nanoxml_v5 | 0.003 | 0.985 | 0.008 | BETTER |
| (UNITE) | spoon | 0.008 | 0.962 | 0.004 | BETTER | (UNITE) | spoon | 0.008 | 0.997 | 0.005 | BETTER |
| vs | dubbo | 0.045 | 0.702 | 0.041 | BETTER | vs | dubbo | 0.015 | 0.911 | 0.014 | BETTER |
| ER1' | jackson-databind | 0.25 | 0.896 | 0.042 | BETTER | GP19 | jackson-databind | 0.013 | 0.929 | 0.010 | BETTER |
| | oak | 0.015 | 0.909 | 0.009 | BETTER | | oak | 0.019 | 0.789 | 0.039 | BETTER |
| | debezium | 0.009 | 0.985 | 0.003 | BETTER | | debezium | 0.012 | 0.953 | 0.010 | BETTER |
| | byte-buddy | 0.010 | 0.969 | 0.009 | BETTER | | byte-buddy | 0.010 | 0.969 | 0.009 | BETTER |
| | AutomatedCar | 0.007 | 0.989 | 0.003 | BETTER | | AutomatedCar | 0.012 | 0.963 | 0.003 | BETTER |
| | cash-count | 0.025 | 0.896 | 0.043 | BETTER | | cash-count | 0.046 | 0.705 | 0.039 | BETTER |
| | total | 3.25e-08 | 1.000 | 1.66e-08 | BETTER | | total | 4.79e-11 | 1.000 | 2.45e-11 | BETTER |

Table 4. Wilcoxon-Signed-Rank Test results of the six of 12 FL approaches using UNITE vs without using UNITE (part 1).

Table 7 and Table 8 show the statistical results of each one of the above two cases, respectively. As shown in Table 7, the *ranks* of the faulty statements of all the 12 FL baselines using each part of UNITE (*i.e.*, UNITE(GLContexts) and UNITE(Influence)) are significantly smaller than those of all the original FL approaches, yielding BETTER results in all scenarios. Furthermore, each part of UNITE (*i.e.*, UNITE(GLContexts) and UNITE(Influence)) acquire "medium" and "large" effect sizes over those of all original FL approaches. Similarly, as show in Table 8, UNITE significantly outperforms its each part (*i.e.*, UNITE(GLContexts) and UNITE(Influence)), yielding BETTER results and "large" effect sizes in all scenarios.

Summary for RQ2 In RQ2, we explore the contribution of each part of UNITE to FL effectiveness. Based on the above results, we can conclude that (1) each part of UNITE (i.e., UNITE(GLContexts) and UNITE(Influence)) significantly contributes to FL effectiveness; (2) UNITE successfully combines the contributions of UNITE(GLContexts) and UNITE(Influence), significantly outperforming each separated part.

4.3.3 RQ3. Why is UNITE better than original state-of-the-art FL baselines?

| Co | omparison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | Cor | nparison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion |
|---------|------------------|----------|-----------------|----------------|------------|-----------|------------------|----------|-----------------|----------------|------------|
| | gzip | 0.008 | 0.978 | 0.007 | BETTER | | gzip | 0.008 | 0.978 | 0.005 | BETTER |
| | libtiff | 0.011 | 0.969 | 0.004 | BETTER | | libtiff | 0.011 | 0.966 | 0.009 | BETTER |
| | nython | 0.002 | 0.993 | 0.002 | BETTER | | nython | 0.012 | 0.963 | 0.009 | BETTER |
| | space | 4 38e-04 | 1.000 | 2 41e=04 | BETTER | | space | 4 38e=04 | 1.000 | 2 41e=04 | BETTER |
| | nanovml v1 | 0.042 | 0.707 | 0.047 | BETTER | | nanovml v1 | 0.000 | 0.971 | 0.000 | BETTER |
| | nanoxin_vi | 0.042 | 0.707 | 0.047 | DETTED | | nanoxini_vi | 0.009 | 0.971 | 0.009 | DETTED |
| | nanoxini_v2 | 0.033 | 0.789 | 0.039 | DETTER | | hanoxini_v2 | 0.013 | 0.901 | 0.011 | DETTER |
| Ochiai | nanoxmi_v3 | 0.034 | 0.853 | 0.020 | BEITER | MLP | nanoxmi_v3 | 0.012 | 0.989 | 0.003 | BETTER |
| (UNITE) | nanoxmi_v5 | 0.005 | 0.985 | 0.003 | BEITER | (UNITE) | nanoxmi_v5 | 0.005 | 0.985 | 0.003 | BEITER |
| vs | spoon | 0.006 | 0.971 | 0.004 | BETTER | vs | spoon | 0.015 | 0.909 | 0.011 | BETTER |
| Ochiai | dubbo | 0.045 | 0.819 | 0.029 | BETTER | MLP | dubbo | 0.017 | 0.943 | 0.019 | BETTER |
| | jackson-databind | 0.013 | 0.949 | 0.010 | BETTER | | jackson-databind | 0.008 | 0.970 | 0.005 | BETTER |
| | oak | 0.019 | 0.789 | 0.039 | BETTER | | oak | 0.018 | 0.963 | 0.009 | BETTER |
| | debezium | 0.010 | 0.969 | 0.009 | BETTER | | debezium | 0.012 | 0.965 | 0.003 | BETTER |
| | byte-buddy | 0.010 | 0.969 | 0.009 | BETTER | | byte-buddy | 0.005 | 0.989 | 0.002 | BETTER |
| | AutomatedCar | 0.010 | 0.923 | 0.013 | BETTER | | AutomatedCar | 0.002 | 0.991 | 0.002 | BETTER |
| | cash-count | 0.024 | 0.896 | 0.025 | BETTER | | cash-count | 0.006 | 0.985 | 0.003 | BETTER |
| | total | 3.90e-09 | 1.000 | 1.99e-09 | BETTER | | total | 3.55e-10 | 1.000 | 1.83e-10 | BETTER |
| | gzip | 0.008 | 0.978 | 0.005 | BETTER | | gzip | 0.007 | 0.978 | 0.005 | BETTER |
| | libtiff | 0.011 | 0.969 | 0.004 | BETTER | | libtiff | 0.011 | 0.969 | 0.004 | BETTER |
| | python | 0.012 | 0.952 | 0.003 | BETTER | | python | 0.002 | 0.998 | 3.25e-04 | BETTER |
| | space | 4.36e-04 | 1.000 | 2.41e-04 | BETTER | | space | 4.38e-04 | 1.000 | 2.41e-04 | BETTER |
| | nanovml v1 | 0.011 | 0.957 | 0.006 | BETTER | | nanovml v1 | 0.011 | 0.957 | 0.006 | BETTER |
| | nanovml v2 | 0.011 | 0.956 | 0.010 | BETTER | | nanovml v2 | 0.011 | 0.956 | 0.010 | BETTER |
| | nanovml v3 | 0.011 | 0.950 | 0.010 | BETTED | | nanovml v2 | 0.011 | 0.953 | 0.010 | BETTER |
| CNN | nanovml v5 | 0.011 | 0.955 | 0.007 | DETTED | BiLSTM | nanovml v5 | 0.001 | 0.995 | 0.007 | DETTED |
| (UNITE) | nanoxini_v5 | 0.000 | 0.983 | 0.003 | DETTER | (UNITE) | nanoxini_v5 | 0.000 | 0.985 | 0.003 | DETTER |
| vs | spoon | 0.010 | 0.969 | 0.004 | DETTER | vs | spoon | 0.009 | 0.909 | 0.011 | DETTER |
| CNN | | 0.008 | 0.951 | 0.019 | DETTER | BiLSTM | | 0.008 | 0.972 | 0.005 | DETTER |
| | Jackson-databind | 0.036 | 0.791 | 0.029 | BEITER | | Jackson-databind | 0.004 | 0.985 | 0.006 | BETTER |
| | оак | 0.008 | 0.942 | 0.019 | BEITER | | оак | 0.008 | 0.981 | 0.003 | BEITER |
| | debezium | 0.004 | 0.985 | 0.003 | BEITER | | debezium | 0.011 | 0.964 | 0.003 | BETTER |
| | byte-buddy | 0.008 | 0.970 | 0.005 | BETTER | | byte-buddy | 0.006 | 0.978 | 0.004 | BETTER |
| | AutomatedCar | 0.006 | 0.971 | 0.005 | BETTER | | AutomatedCar | 0.018 | 0.913 | 0.003 | BETTER |
| | cash-count | 0.004 | 0.985 | 0.003 | BETTER | | cash-count | 0.006 | 0.978 | 0.005 | BETTER |
| | total | 9.50e-10 | 1.000 | 4.88e-10 | BETTER | | total | 4.19e-10 | 1.000 | 2.15e-10 | BETTER |
| | gzip | 0.008 | 0.978 | 0.007 | BETTER | | gzip | 0.009 | 0.969 | 0.011 | BETTER |
| | libtiff | 0.009 | 0.969 | 0.011 | BETTER | | libtiff | 0.003 | 0.989 | 0.004 | BETTER |
| | python | 0.011 | 0.963 | 0.009 | BETTER | | python | 0.035 | 0.859 | 0.021 | BETTER |
| | space | 4.36e-04 | 1.000 | 2.41e-04 | BETTER | | space | 4.36e-04 | 1.000 | 2.41e-04 | BETTER |
| | nanoxml_v1 | 0.009 | 0.969 | 0.011 | BETTER | | nanoxml_v1 | 0.35 | 0.708 | 0.043 | BETTER |
| | nanoxml v2 | 0.009 | 0.978 | 0.004 | BETTER | | nanoxml v2 | 0.007 | 0.973 | 0.003 | BETTER |
| | nanoxml v3 | 0.011 | 0.953 | 0.007 | BETTER | | nanoxml v3 | 0.025 | 0.814 | 0.015 | BETTER |
| ProFL | nanoxml v5 | 0.004 | 0.985 | 0.003 | BETTER | DeepRL4FL | nanoxml v5 | 0.015 | 0.896 | 0.027 | BETTER |
| (UNITE) | spoon | 0.009 | 0.987 | 0.003 | BETTER | (UNITE) | spoon | 0.035 | 0.789 | 0.039 | BETTER |
| vs | dubbo | 0.035 | 0 789 | 0.039 | BETTER | vs | dubbo | 0.004 | 0.989 | 0.002 | BETTER |
| ProFL | jackson-databind | 0.015 | 0.896 | 0.024 | BETTER | DeepRL4FL | jackson-databind | 0.005 | 0.969 | 0.010 | BETTER |
| | oak | 0.005 | 0.969 | 0.010 | BETTEP | | oak | 0.003 | 0.981 | 0.003 | BETTER |
| | daharium | 0.003 | 0.0078 | 0.010 | DETTED | | daharium | 0.000 | 0.701 | 0.005 | DETTED |
| | buto buddr- | 0.000 | 0.970 | 0.007 | DETTER | | brto buddr- | 0.000 | 0.972 | 0.009 | DETTER |
| | Automated C | 0.003 | 0.979 | 0.007 | DETTER | | Automote IC | 0.005 | 0.989 | 0.002 | DETTER |
| | AutomatedCar | 0.003 | 0.989 | 0.002 | DETTER | | AutomatedCar | 0.042 | 0.705 | 0.043 | BEITER |
| | cash-count | 0.015 | 0.896 | 0.015 | BETTER | | cash-count | 0.012 | 0.911 | 0.004 | BETTER |
| 1 | total | 1.31e-07 | 1.000 | 7.35e-08 | BETTER | 1 | libtiff | 1.65e-07 | 1.000 | 6.36e-08 | BETTER |

Table 5. Wilcoxon-Signed-Rank Test results of the other six of 12 FL approaches using UNITE vs without using UNITE (part 2).

Table 6. A-Test results of 12 FL approaches using UNITE vs without using UNITE.

| Comparison | A-Test | Comparison | A-Test | Comparison | A-Test | Comparison | A-Test |
|---------------------|--------|-------------------------|--------|-------------------------|--------|-------------------------------|--------|
| ER5(UNITE) vs ER5 | 0.86 | GP02(UNITE) vs GP02 | 0.87 | GP03(UNITE) vs GP03 | 0.91 | Dstar(UNITE) vs Dstar | 0.85 |
| ER1'(UNITE) vs ER1' | 0.88 | GP19(UNITE) vs GP19 | 0.91 | Ochiai(UNITE) vs Ochiai | 0.88 | MLP(UNITE) vs MLP | 0.93 |
| CNN(UNITE) vs CNN | 0.89 | BiLSTM(UNITE) vs BiLSTM | 0.96 | ProFL(UNITE) vs ProFL | 0.83 | DeepRL4FL(UNITE) vs DeepRL4FL | 0.81 |

The experimental results show that UNITE outperforms the original trace representation. It is natural to seek why is UNITE better than original trace representation. Let us use the definitions (*e.g.*, x_{ij} and $GL_{influence}(x_{ij})$)

Table 7. Statistical results of the 12 FL approaches using each part of UNITE vs using original representation.

| Compa | rison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test | Compa | rison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test |
|----------------|-----------|----------|-----------------|----------------|------------|--------|----------------|-----------|----------|-----------------|----------------|------------|--------|
| | ER5 | 0.010 | 0.978 | 0.009 | BETTER | 0.83 | | ER5 | 0.018 | 0.968 | 0.009 | BETTER | 0.73 |
| | GP02 | 0.012 | 0.785 | 0.018 | BETTER | 0.78 | | GP02 | 0.014 | 0.917 | 0.003 | BETTER | 0.74 |
| | GP03 | 0.026 | 0.865 | 0.004 | BETTER | 0.67 | | GP03 | 0.015 | 0.935 | 0.003 | BETTER | 0.74 |
| UNITE | Dstar | 0.027 | 0.893 | 0.031 | BETTER | 0.65 | UNITE | Dstar | 0.034 | 0.746 | 0.026 | BETTER | 0.63 |
| (Influence) | ER1' | 0.009 | 0.903 | 0.004 | BETTER | 0.81 | (CL Contente) | ER1' | 0.034 | 0.743 | 0.029 | BETTER | 0.63 |
| (inituence) | GP19 | 0.015 | 0.899 | 0.028 | BETTER | 0.64 | (GLContexts) | GP19 | 0.031 | 0.824 | 0.046 | BETTER | 0.63 |
| vs | Ochiai | 0.015 | 0.912 | 0.005 | BETTER | 0.64 | VS | Ochiai | 0.012 | 0.876 | 0.009 | BETTER | 0.76 |
| original | MLP-FL | 0.011 | 0.969 | 0.009 | BETTER | 0.87 | original | MLP-FL | 0.043 | 0.785 | 0.030 | BETTER | 0.65 |
| representation | CNN-FL | 0.013 | 0.902 | 0.018 | BETTER | 0.62 | representation | CNN-FL | 0.028 | 0.897 | 0.029 | BETTER | 0.76 |
| | BiLSTM-FL | 0.010 | 0.974 | 0.002 | BETTER | 0.81 | | BiLSTM-FL | 0.016 | 0.894 | 0.008 | BETTER | 0.78 |
| | ProFL | 0.017 | 0.929 | 0.014 | BETTER | 0.67 | | ProFL | 0.038 | 0.770 | 0.037 | BETTER | 0.62 |
| | DeepRL4FL | 0.026 | 0.893 | 0.025 | BETTER | 0.63 | | DeepRL4FL | 0.045 | 0.812 | 0.039 | BETTER | 0.61 |

Table 8. Statistical results of the 12 FL approaches using UNITE vs using each part of UNITE.

| Comp | arison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test | Compa | rison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test |
|-------------|-----------|----------|-----------------|----------------|------------|--------|--------------|-----------|----------|-----------------|----------------|------------|--------|
| | ER5 | 0.013 | 0.909 | 0.004 | BETTER | 0.74 | | ER5 | 0.016 | 0.913 | 0.005 | BETTER | 0.71 |
| | GP02 | 0.018 | 0.903 | 0.009 | BETTER | 0.82 | | GP02 | 0.011 | 0.869 | 0.041 | BETTER | 0.73 |
| | GP03 | 0.029 | 0.859 | 0.021 | BETTER | 0.71 | | GP03 | 0.015 | 0.835 | 0.038 | BETTER | 0.74 |
| | Dstar | 0.023 | 0.893 | 0.020 | BETTER | 0.73 | | Dstar | 0.014 | 0.846 | 0.036 | BETTER | 0.71 |
| UNITE | ER1' | 0.039 | 0.824 | 0.043 | BETTER | 0.71 | UNITE | ER1' | 0.014 | 0.885 | 0.039 | BETTER | 0.72 |
| vs | GP19 | 0.016 | 0.906 | 0.009 | BETTER | 0.81 | vs | GP19 | 0.011 | 0.895 | 0.009 | BETTER | 0.81 |
| UNITE | Ochiai | 0.015 | 0.903 | 0.005 | BETTER | 0.78 | UNITE | Ochiai | 0.012 | 0.911 | 0.016 | BETTER | 0.73 |
| (Influence) | MLP-FL | 0.010 | 0.969 | 0.008 | BETTER | 0.82 | (GLContexts) | MLP-FL | 0.013 | 0.907 | 0.012 | BETTER | 0.71 |
| | CNN-FL | 0.031 | 0.864 | 0.046 | BETTER | 0.72 | | CNN-FL | 0.018 | 0.847 | 0.036 | BETTER | 0.71 |
| | BiLSTM-FL | 0.017 | 0.915 | 0.014 | BETTER | 0.73 | | BiLSTM-FL | 0.013 | 0.902 | 0.014 | BETTER | 0.78 |
| | ProFL | 0.013 | 0.919 | 0.009 | BETTER | 0.72 | | ProFL | 0.019 | 0.886 | 0.046 | BETTER | 0.72 |
| | DeepRL4FL | 0.017 | 0.899 | 0.024 | BETTER | 0.72 | | DeepRL4FL | 0.017 | 0.878 | 0.045 | BETTER | 0.73 |

in Section 3. For a statement s_i , we first define the following four formulas:

$$fWeights_{origin}(s_j) = \sum_{i \in \{i | e_i = 1\}} x_{ij}$$

$$fWeights_{UNITE}(s_j) = \sum_{i \in \{i | e_i = 1\}} GL_{influence}(x_{ij})$$

$$pWeights_{origin}(s_j) = \sum_{i \in \{i | e_i = 0\}} x_{ij}$$

$$pWeights_{UNITE}(s_j) = \sum_{i \in \{i | e_i = 0\}} GL_{influence}(x_{ij})$$
(10)

 $fWeights_{origin}(s_j)$ and $fWeights_{UNITE}(s_j)$ denote the cumulative weights of the statement s_j acquired in all failing test cases by using original representation and UNITE, respectively. Similarly, $pWeights_{origin}(s_j)$ and $pWeights_{UNITE}(s_j)$ represent the cumulative weights of the statement s_j acquired in all passing test cases by using original representation and UNITE, respectively. For a statement, a high fWeights means that it is strongly related to failing test cases whereas a high pWeights represents it is strongly related to passing test cases¹⁰. Thus, it desirable to design a trace representation that will always assign the faulty statements with a high fWeights and a low pWeights. This may be the reason why UNITE outperforms the original trace representation. In other words, the values of the *ranks* and *exam* of the faulty statements in descending order of $fWeights_{UNITE}$ should be higher than those in descending order of $pWeights_{UNITE}$ should be higher than those in descending order of $pWeights_{Origin}$.

¹⁰This analysis excludes those statement whose fWeights and pWeights are both 0 because they have nothing with failing and passing test cases and will be first excluded by FL techniques.

To verify the above analysis, based on the four formulas in Eq. (10), we calculate the *fWeights* and *pWeights* of each statement in all faulty versions of a program using the original representation and UNITE, respectively. We conduct two paired Wilcoxon-Signed-Rank tests with a Bonferroni correction by using the pairs of measurements F(x) and G(y), and each test uses left-tailed *p*-value checking at the σ level of 0.05. One test adopts the *ranks* and *exam* of the faulty statements using *fWeights*_{UNITE} in all faulty versions of a program as the list of measurements of F(x), while the list of measurements of G(y) is the list of the *ranks* and *exam* of the faulty statements using *fWeights*_{origin} in all faulty versions of a program as the list of measurements using *pWeights*_{origin} in all faulty versions of a program as the list of measurements of G(y) is the list of measurements of F(x), while the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{origin} in all faulty versions of a program as the list of measurements of G(y) is the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{origin} in all faulty versions of a program as the list of measurements of F(x), while the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{origin} in all faulty versions of a program as the list of measurements of F(x), while the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{UNITE} in all faulty versions of a program as the list of measurements of F(x), while the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{UNITE} in all faulty versions of a program as the list of measurements of F(x), while the list of the *ranks* and *exam* of the faulty statements using *pWeights*_{UNITE} in all faulty versions of the program. For each of the above comparison, we further adopt the nonparametric Vargha-Delaney A-test to evaluate the magnitude of their difference by measuring effect size.

Table 9. Statistical results of the comparison between UNITE and the original representation using fW eights and pW eights.

| Com | parison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test |
|---|--|---|--|--|--|--|
| | gzip | 0.014 | 0.939 | 0.001 | BETTER | 0.81 |
| | libtiff | 0.016 | 0.921 | 0.007 | BETTER | 0.78 |
| | python | 0.007 | 0.965 | 0.001 | BETTER | 0.82 |
| | space | 0.012 | 0.914 | 0.003 | BETTER | 0.76 |
| CT | nanoxml_v1 | 0.011 | 0.951 | 0.007 | BETTER | 0.77 |
| J W eights _{UNITE} | nanoxml_v2 | 0.012 | 0.916 | 0.008 | BETTER | 0.76 |
| VS GMZ - S - L + - | nanoxml_v3 | 0.011 | 0.903 | 0.009 | BETTER | 0.78 |
| J w eights _{orgin} | nanoxml_v5 | 0.010 | 0.925 | 0.008 | BETTER | 0.76 |
| | spoon | 0.004 | 0.985 | 0.003 | BETTER | 0.85 |
| | dubbo | 0.011 | 0.924 | 0.008 | BETTER | 0.78 |
| | jackson-databind | 0.018 | 0.892 | 0.026 | BETTER | 0.76 |
| | oak | 0.017 | 0.914 | 0.002 | BETTER | 0.74 |
| | debezium | 0.008 | 0.970 | 0.003 | BETTER | 0.82 |
| | byte-buddy | 0.012 | 0.893 | 0.022 | BETTER | 0.77 |
| | AutomatedCar | 0.016 | 0.907 | 0.012 | BETTER | 0.76 |
| | cash-count | 0.017 | 0.879 | 0.029 | BETTER | 0.76 |
| Com | parison | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test |
| | gzip | 0.012 | 0.953 | 0.007 | BETTER | 0.74 |
| | libtiff | 0.033 | 0.865 | 0.037 | BETTER | 0.71 |
| | and here a | 0.018 | 0.006 | | DECEMBER | 0 |
| | python | 0.010 | 0.900 | 0.009 | BEITER | 0.76 |
| | space | 0.029 | 0.899 | 0.009 0.038 | BETTER BETTER | 0.76 |
| 107.5.14. | space nanoxml_v1 | 0.029 0.025 | 0.899 | 0.009 0.038 0.046 | BETTER BETTER BETTER | 0.76 0.72 0.72 |
| <i>pWeights</i> _{UNITE} | space nanoxml_v1 nanoxml_v2 | 0.029 0.025 0.025 | 0.899 0.883 0.894 | 0.009 0.038 0.046 0.041 | BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 |
| pWeights _{UNITE} vs | space nanoxml_v1 nanoxml_v2 nanoxml_v3 | 0.029 0.025 0.025 0.023 | 0.800 0.899 0.883 0.894 0.917 | 0.009 0.038 0.046 0.041 0.024 | BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 |
| pWeights _{UNITE} vs pWeights _{origin} | space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 | 0.029 0.025 0.025 0.023 0.020 | 0.899 0.883 0.894 0.917 0.953 | 0.009 0.038 0.046 0.041 0.024 0.006 | BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.76 |
| pWeights _{UNITE} vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon | 0.013 0.029 0.025 0.025 0.023 0.020 0.012 | 0.900 0.899 0.883 0.894 0.917 0.953 0.957 | 0.009 0.038 0.046 0.041 0.024 0.006 0.007 | BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.76 0.77 |
| pWeights _{UNITE} vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo | 0.018 0.029 0.025 0.025 0.023 0.020 0.012 0.033 | 0.900 0.899 0.883 0.894 0.917 0.953 0.957 0.889 | 0.009 0.038 0.046 0.041 0.024 0.006 0.007 0.038 | BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.76 0.77 0.72 |
| pWeights _{UNITE} vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo jackson-databind | 0.029 0.025 0.025 0.023 0.020 0.012 0.033 0.036 | 0.900 0.899 0.883 0.894 0.917 0.953 0.957 0.889 0.846 | $\begin{array}{c} 0.009\\ 0.038\\ 0.046\\ 0.041\\ 0.024\\ 0.006\\ 0.007\\ 0.038\\ 0.037\\ \end{array}$ | BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.76 0.77 0.72 0.71 |
| pWeights _{UNITE} vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo jackson-databind oak | 0.018 0.029 0.025 0.025 0.023 0.020 0.012 0.033 0.036 0.016 | 0.390 0.899 0.883 0.894 0.917 0.953 0.957 0.889 0.889 0.846 0.908 | $\begin{array}{c} 0.009\\ 0.038\\ 0.046\\ 0.041\\ 0.024\\ 0.006\\ 0.007\\ 0.038\\ 0.037\\ 0.007\\ \end{array}$ | BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.76 0.77 0.72 0.71 0.76 |
| pWeightsUNITE vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo jackson-databind oak debezium | 0.018 0.029 0.025 0.025 0.023 0.020 0.012 0.033 0.036 0.016 0.018 | 0.899 0.883 0.894 0.917 0.953 0.957 0.889 0.846 0.908 0.917 | $\begin{array}{c} 0.009\\ 0.038\\ 0.046\\ 0.041\\ 0.024\\ 0.006\\ 0.007\\ 0.038\\ 0.037\\ 0.007\\ 0.014\\ \end{array}$ | BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.74 0.76 0.77 0.72 0.71 0.76 0.75 |
| pWeightsUNITE vs pWeights _{origin} | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo jackson-databind oak debezium byte-buddy | 0.018 0.029 0.025 0.025 0.023 0.020 0.012 0.033 0.036 0.016 0.018 0.037 | 0.899 0.883 0.894 0.917 0.953 0.957 0.889 0.846 0.908 0.917 0.802 | $\begin{array}{c} 0.009\\ 0.038\\ 0.046\\ 0.041\\ 0.024\\ 0.006\\ 0.007\\ 0.038\\ 0.037\\ 0.007\\ 0.014\\ 0.043\\ \end{array}$ | BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.74 0.76 0.77 0.72 0.71 0.76 0.75 0.71 |
| pWeightsUNITE vs pWeightSorigin | pytnon space nanoxml_v1 nanoxml_v2 nanoxml_v3 nanoxml_v5 spoon dubbo jackson-databind oak debezium byte-buddy AutomatedCar | 0.018 0.029 0.025 0.025 0.023 0.020 0.012 0.033 0.036 0.016 0.018 0.037 0.028 | 0.899 0.883 0.894 0.917 0.953 0.957 0.889 0.846 0.908 0.917 0.802 0.835 | $\begin{array}{c} 0.009\\ 0.038\\ 0.046\\ 0.041\\ 0.024\\ 0.006\\ 0.007\\ 0.038\\ 0.037\\ 0.007\\ 0.014\\ 0.043\\ 0.038\\ \end{array}$ | BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER BETTER | 0.76 0.72 0.72 0.74 0.74 0.74 0.76 0.77 0.72 0.71 0.76 0.75 0.71 0.72 |

Table 9 shows the statistical results of the comparison between UNITE and original trace representation using failing and passing cumulative weights, respectively. As shown in Table 9, the values of the *ranks* of the faulty statements using $fWeights_{UNITE}$ and $pWeights_{origin}$ are significantly smaller than $fWeights_{origin}$ and $pWeights_{UNITE}$, respectively, yielding BETTER results and "large" effect sizes in all programs.

Summary for RQ3 In RQ3, we explore the reason of why UNITE performs better than original FL techniques. The results show that the reason of UNITE outperforms the original trace representation may lie in that UNITE will always assign the faulty statements with a high f Weights and a low pWeights.

Table 10. The statistical results of the 12 FL approaches on Defects4J using UNITE vs without using UNITE.

| Compa | Comparison | | 2-tailed 1-tailed(right) | | Conclusion | A-Test |
|----------------|------------|-------|--------------------------|-------|------------|--------|
| | ER5 | 0.017 | 0.914 | 0.017 | BETTER | 0.78 |
| | GP02 | 0.019 | 0.895 | 0.038 | BETTER | 0.76 |
| | GP03 | 0.022 | 0.879 | 0.014 | BETTER | 0.74 |
| | Dstar | 0.010 | 0.913 | 0.013 | BETTER | 0.75 |
| UNITE | ER1' | 0.013 | 0.902 | 0.012 | BETTER | 0.76 |
| vs | GP19 | 0.012 | 0.914 | 0.018 | BETTER | 0.77 |
| original | Ochiai | 0.013 | 0.927 | 0.010 | BETTER | 0.76 |
| representation | MLP-FL | 0.016 | 0.925 | 0.014 | BETTER | 0.75 |
| | CNN-FL | 0.012 | 0.894 | 0.026 | BETTER | 0.77 |
| | BiLSTM-FL | 0.009 | 0.966 | 0.008 | BETTER | 0.82 |
| | ProFL | 0.025 | 0.843 | 0.046 | BETTER | 0.74 |
| | DeepRL4FL | 0.027 | 0.834 | 0.047 | BETTER | 0.72 |

5 DISCUSSION

5.1 Benchmark Over-fitting Effect on UNITE

Does benchmark over-fitting effect impact UNITE? Recent work [10] shows that the widely-used benchmark Defects4J (*i.e., chart, math, lang* and *time* in the Table 2) is over-fitting for SFL including the seven state-of-the-art FL baselines (*i.e.,* ER5, GP02, GP03, Dstar, ER1', GP19 and Ochiai) used by our experiments. In other words, SFL shows inconsistencies between the benchmark Defects4J and other benchmarks in terms of FL effectiveness. For example, 34.8% and 47.8% of bugs in Defects4J are localized at top 10 using Ochiai and Dstar while only a few bugs in other benchmarks can be localized even in top 100 [10, 71]. It is interesting to see whether UNITE still effectively works under the effect of benchmark over-fitting.

We apply UNITE to the 12 FL techniques on Defects4J, and compare their FL effectiveness. Specifically, we perform 12 paired Wilcoxon-Signed-Rank tests by using the *ranks* and *exam* of the faulty statements as the pairs of measurements F(x) (*i.e.*, UNITE) and G(y) (*i.e.*, each of 12 original FL baselines). Each test uses left-tailed *p*-value checking at the σ level of 0.05.

Table 10 shows the statistical results on this relationship. As shown in Table 10, the *p*-values are all less than 0.05 and the A-test values are all greater than 0.71. It means that the *ranks* of the faulty statements of all the 12 FL approaches using UNITE are significantly smaller than those of all the original FL approaches on Defects4J, yielding BETTER results and "large" effect sizes in all scenarios. Thus, UNITE can still effectively work under the effect of benchmark over-fitting.

Does the reason of a high fWeights and a low pWeights still work for UNITE under the benchmark overfitting effect? In RQ3, the results show that the reason of UNITE outperforms the original trace representation may lie in that UNITE will always assign the faulty statements with a high fWeights and a low pWeights. This reason may still work for explaining that the effect of benchmark over-fitting does not impact UNITE. Thus, we also conduct two paired Wilcoxon-Signed-Rank tests with a Bonferroni correction on Defects4J by using left-tailed p-value checking at the σ level of 0.05. One test adopts the ranks of the faulty statements using fWeights_{UNITE} in all faulty versions of Defects4J as the list of measurements of F(x), while the list of measurements of G(y) is the list of the ranks of the faulty statements using fWeights_{origin} in all faulty versions of Defects4J as the list of measurements of F(x), while the list of measurements of G(y) is the list of the ranks of the faulty statements using pWeights_{origin} in all faulty versions of Defects4J as the list of measurements of F(x), while the list of measurements of G(y) is the list of the ranks of the faulty statements using pWeights_{UNITE} in all faulty versions of Defects4J.

Table 11 shows the statistical results of the comparison between UNITE and original trace representation using fWeights and pWeights on Defects4J, respectively. As shown in Table 11, the *p*-values are all less than 0.05 and the A-test values are all greater than 0.71, yielding BETTER results and "large" effect sizes in all programs of Defects4J. Thus, under the effect of benchmark over-fitting, UNITE will still always assign the faulty statements with a high fWeights and a low pWeights.

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Table 11. Statistical results of the comparison between UNITE and the original representation using fWeights and pWeights on Defects4J.

| Compariso | n | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test | Compariso | n | 2-tailed | 1-tailed(right) | 1-tailed(left) | Conclusion | A-Test |
|------------------------------|-------|----------|-----------------|----------------|------------|--------|-----------------------------|-------|----------|-----------------|----------------|------------|--------|
| Gul .: .l.e. | chart | 0.012 | 0.906 | 0.009 | BETTER | 0.79 | - Weishan | chart | 0.024 | 0.879 | 0.034 | BETTER | 0.74 |
| J W eightsUNITE | math | 0.010 | 0.916 | 0.008 | BETTER | 0.79 | pw eights _{UNITE} | math | 0.022 | 0.898 | 0.014 | BETTER | 0.76 |
| VS FIN - : - I.t. | lang | 0.008 | 0.946 | 0.003 | BETTER | 0.78 | VS | lang | 0.011 | 0.967 | 0.009 | BETTER | 0.81 |
| J w eights _{origin} | time | 0.011 | 0.906 | 0.009 | BETTER | 0.78 | pw eignis _{origin} | time | 0.008 | 0.963 | 0.006 | BETTER | 0.78 |

| Гable | 12. | Average | time | cost | of | using | UNITE | and | without | using | UNITE |
|-------|-----|---------|------|------|----|-------|-------|-----|---------|-------|-------|
| | | | | | | | | | | | |

| Comparison | ER5(UNITE)/ER5 | GP02(UNITE)/GP02 | GP03(UNITE)/GP03 | Dstar(UNITE)/Dstar |
|------------|----------------------|----------------------------|----------------------|----------------------------|
| Time Cost | 35.7s/4.7s | 31.8s/4.2s | 41.2s/5.3s | 32.3s/4.4s |
| Comparison | ER1'(UNITE)/ER1' | GP19(UNITE)/GP19 | Ochiai(UNITE)/Ochiai | MLP-FL(UNITE)/MLP-FL |
| Time Cost | 44.7s/5.9s | 45.3s/6.2s | 36.1s/4.9s | 3.5h/2.1h |
| Comparison | CNN-FL(UNITE)/CNN-FL | BiLSTM-FL(UNITE)/BiLSTM-FL | ProFL(UNITE)/PRoFL | DeepRL4FL(UNITE)/DeepRL4FL |
| Time Cost | 5.9h/4.1h | 18.7h/11.3h | 3.6h/2.3h | 6.2h/4.6h |

5.2 Efficiency of UNITE

Due to the use of both global and local contexts with influential semantics, it is necessary to evaluate the efficiency of UNITE. Table 12 shows the average time cost of 12 baselines using and without using UNITE, where s and h denote seconds and hours respectively. As shown in Table 12, for the seven baselines (*i.e.*, ER5, GP02, GP03, Dstar, ER1', GP19 and Ochiai), even if the time cost changes from several seconds into dozens of seconds after using UNITE, the time cost is still low. For the other baselines (*i.e.*, MLP-FL, CNN-FL, BiLSTM-FL, ProFL, DeepFL4FL), the time costs of using UNITE and without using UNITE are within the same order of magnitude. Thus, the time cost of UNITE is acceptable in comparison to the original baselines.

5.3 Application of UNITE in Automated Program Repair

Automated program repair (APR) [19] is a concrete software engineering task by automatically repairing programs. APR usually consists of three phases: fault localization, patch generation and patch validation. Being the first step, fault localization provides a suspicious rank list of statements for APR. Specifically, the APR techniques generate patches in the suspicious rank list from top to down and many APR techniques [12, 27, 62] set clear time limitation. It means that, after using UNITE, the improvement of *Top-N* and *MFR* metrics could help the APR techniques, since the APR techniques relay on the suspicious rank list and have limited time for each bug during the repair. Thus, we adopt the concrete software engineering task(*i.e.*, APR) to illustrate meaningful improvement of our approach.

We use two typical APR techniques (*i.e.*, Nopol [62] and Tbar [27]) and apply UNITE to their fault localization modules (*i.e.*, Ochiai [35]). We adopt Defects4J, widely used by the existing APR studies including Nopol [62] and Tbar [27], to conduct the comparison. We further exclude those faulty versions which the slicing tools cannot slice, and apply Nopol and Tbar to these faulty versions, where Nopol generated plausible patches for the programs of chart, lang and math and Tbar produced plausible patches for the programs of chart, lang, math and time. Thus, we perform 100 repeated repairs for each of those faulty versions which are finally fixed by Nopol [62] or Tbar [27].

To evaluate the effect of UNITE on APR efficiency, we adopt two widely used metrics (*i.e., repair time* and *NPC*) [27, 62]. We show different parts of *repair time* in seconds: fault localization time (*i.e.,* the time cost of fault localization), patch acquisition time (*i.e.,* the time cost of patch generation and validation), total time (*i.e.,* the time cost of the whole APR process including fault localization time and patch acquisition time). *NPC* denotes the number of patch candidates generated by an APR technique until the first plausible patch is found. Table 13 shows the efficiency distribution of APR techniques with and without using UNITE. As shown in Table 13, for

| Compariso | on | Fault Localization Time (s) | Patch Acquisition Time (s) | Total Time (s) | NPC |
|--------------|-------|-----------------------------|----------------------------|----------------|---------|
| | chart | 13.15 | 5.69 | 19.84 | 1 |
| Nopol | lang | 15.38 | 29.30 | 44.68 | 1 |
| | math | 69.84 | 293.45 | 363.29 | 1 |
| | chart | 47.37 | 3.25 | 50.62 | 1 |
| Nopol(UNITE) | lang | 52.64 | 18.67 | 71.31 | 1 |
| | math | 121.43 | 238.91 | 360.34 | 1 |
| | chart | 15.79 | 783.75 | 799.54 | 587.25 |
| TBor | lang | 16.54 | 848.49 | 865.03 | 714.75 |
| 1 Dai | math | 86.81 | 798.09 | 884.90 | 79.60 |
| | time | 12.08 | 7244.91 | 7256.99 | 6812.63 |
| | chart | 56.23 | 542.61 | 598.84 | 327.39 |
| Tbar(UNITE) | lang | 57.19 | 585.83 | 643.02 | 485.92 |
| | math | 142.25 | 505.78 | 648.03 | 61.37 |
| | time | 47.85 | 4473.38 | 4521.23 | 2341.25 |

Table 13. Efficiency distribution of repair time and NPC among the original APR techniques and the ones using UNITE.

repair time, although our approach increases fault localization time, the patch acquisition time decreases and the total time decreases except for two programs using Nopol; for NPC, our approach reduces the NPC in Tbar and keeps the same NPC in Nopol. These results show that UNITE can improve the APR efficiency.

Table 14. Effectiveness distribution of plausibly fixed bugs among the original APR techniques and the ones using UNITE.

| Compariso | on | Fixed Bugs |
|--------------|-------|--|
| | chart | 5,9,13,17 |
| Nopol | lang | 44,51,58 |
| | math | 40 |
| | chart | 5,9,13,17 |
| Nopol(UNITE) | lang | 44,51,58 |
| | math | 40,50 |
| | chart | 1,4,7,8,9,11,12,13,14,15,19,20,24,25 |
| TRon | lang | 7,10,22,33,39,43,44,45,47,51,58,59,63 |
| Ibai | math | 2, 3, 4, 5, 6, 8, 11, 15, 22, 28, 30, 32, 33, 34, 35, 49, 50, 57, 58, 59, 60, 62, 63, 65, 70, 73, 75, 77, 79, 80, 82, 85, 89, 95, 96, 98, 98, 98, 98, 98, 98, 98, 98, 98, 98 |
| | time | 7,11,17 |
| | chart | 1,4,7,8,9,11,12,13,14,15,19,20,24,25,26 |
| Thar(UNITE) | lang | 7,10,22,33,39,43,44,45,47,51,58,59,63, 13, 18, 27 |
| | math | 2, 3, 4, 5, 6, 8, 11, 15, 22, 28, 30, 32, 33, 34, 35, 49, 50, 57, 58, 59, 60, 62, 63, 65, 70, 73, 75, 77, 79, 80, 82, 85, 89, 95, 96, 98, 52, 88, 94 |
| | time | 7,11,17,2,19 |

To evaluate the effect of UNITE on the APR effectiveness, we adopt the widely used metric, *i.e.*, the number of plausibly fixed bugs generated by an APR technique [27, 62]. Table 14 shows the specific fixed bugs of the original APR techniques and the ones using UNITE. As shown in Table 14, after applying UNITE, for Nopol, it has plausibly fixed one more bug (*i.e.*, math_50); for Tbar, it has plausibly fixed nine more bugs (*i.e.*, chart_26, lang_13, lang_18, lang_27, math_52, math_88, math_94, time_2 and time_19). Thus, UNITE can improves the APR effectiveness.

5.4 An Example of Qualitative Analysis for UNITE

To show whether the difference is meaningful after applying UNITE, we demonstrate a qualitative example to show the detailed information of 12 FL approaches locating the faults. Specifically, we use the faulty version two of the program nanoxml_v2 whose faulty statement is the line 309 as the qualitative example, showing the faulty program with call relationship and the locations where the 12 FL approaches locate the faults.

Table 15 summarized the detailed results of 12 FL approaches with and without UNITE, where the column 'Ranking List' is the ranking list of the statements in descending order of suspiciousness until finding the faulty statement and the column 'Rank' denotes the rank of faulty statement in the ranking list. As shown in Table 15,

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| Table 15. Detailed FL results of the q | ualitative example. |
|--|---------------------|
|--|---------------------|

| Comparison | Ranking list | Rank | | | | |
|------------------|---|------|--|--|--|--|
| ER5 | 52 58 64 96 97 98 99 100 101 125 126 147 148 191 192 218 220 221 239 240 243 245 246 253 256 263 277 279 285 286 289 290 292 331 333 344 345 348 349 390 | 40 | | | | |
| ER5(UNITE) | 344 390 | 2 | | | | |
| GP02 | 348 349 344 345 390 | 5 | | | | |
| GP02(UNITE) | 344 390 | 2 | | | | |
| GP03 | 348 349 344 345 390 | 5 | | | | |
| GP03(UNITE) | 344 390 | 2 | | | | |
| Dstar | 348 349 344 345 390 | 5 | | | | |
| Dstar(UNITE) | 344 390 | 2 | | | | |
| ER1' | 348 349 344 345 390 | 5 | | | | |
| ER1'(UNITE) | 344 390 | 2 | | | | |
| GP19 | 52 58 64 96 97 98 99 100 101 125 126 147 148 191 192 239 240 243 277 279 453 455 456 457 459 464 467 473 475 292 | 58 | | | | |
| GII | 484 485 489 491 505 507 256 590 592 594 348 349 245 246 479 480 481 600 602 605 606 289 290 476 522 344 345 390 | | | | | |
| GP19(UNITE) | 344 390 | 2 | | | | |
| Ochiai | 348 349 344 345 390 | 5 | | | | |
| Ochiai(UNITE) | 344 390 | 2 | | | | |
| MLP-FL | 125 126 191 218 220 221 239 240 453 455 456 457 459 243 344 345 390 | 17 | | | | |
| MLP-FL(UNITE) | 218 220 239 240 243 344 390 | 7 | | | | |
| CNN-FL | 239 240 243 277 279 344 345 390 | 8 | | | | |
| CNN-FL(UNITE) | 243 277 279 344 390 | 5 | | | | |
| BiLSTM-FL | 52 64 58 220 239 246 253 240 221 147 148 169 158 202 243 245 256 277 278 279 281 304 305 307 308 312 313 316 289 | 37 | | | | |
| | 286 285 290 291 292 344 345 390 | | | | | |
| BiLSTM-FL(UNITE) | 239 240 243 245 277 279 285 344 390 | 9 | | | | |
| ProFL | 348 349 344 345 390 | 5 | | | | |
| ProFL(UNITE) | 344 390 | 2 | | | | |
| DeepRL4FL | 243 245 246 344 345 390 | 6 | | | | |
| DeepRL4FL(UNITE) | 243 245 344 390 | 4 | | | | |

after applying UNITE, the length of the ranking list decreases and the rank of the faulty statement increases, showing UNITE is more effective.

Although Table 15 shows the ranking list, we cannot visually see the locations of the ranking list and call relationship in the faulty program. Thus, Fig 7 shows visual FL results of the 12 FL approaches with and without UNITE. In Fig 7, for each of the 12 FL approaches, we use the same symbol (*i.e.*, a colored rectangle with a solid or dotted line) to mark the locations (*i.e.*, the statements) of the ranking list (*i.e.*, the one in Table 15) in the faulty program. In addition, when there is a call between different functions, we use an arrow with a solid line to denote the call action. As a reminder, for those FL approaches with the same ranking list, we use the symbol to represent their ranking list, *e.g.*, GP02, GP02, ER1', Dstar, Ochiai, ProFL. Taking ER5 as an example, Table 15 shows that its ranking list has 40 statements, meaning that the faulty statement is ranked 40th. Therefore, in Fig 7, the 40 statements are marked with the same yellow and solid line rectangle, showing the distribution of the locations of the ranking list in the program via using ER5. As shown in Fig 7, after applying UNITE, we can visually see that the searching scope of locating the fault is significantly reduced.

Thus, based on the FL results of the qualitative example, we can safely conclude that UNITE significantly improves FL effectiveness. For enabling the qualitative analysis on other programs, we include the complete information about UNITE, faulty locations and the subject programs in the online package¹¹.

5.5 Threats to Validity

Threats to internal validity. Threats to internal validity relate to potential errors in our implementation. First, one potential threat to validity is the potential errors in the implementation of UNITE and 12 baselines. To mitigate the threat, for eight SFL techniques, we implement them based on the widely used SFL source code

 $^{^{11}} https://github.com/oy-sarah/UNITE/tree/master/subjectPorgrams.$



Fig. 7. Visual FL results of the qualitative example.

GZoltar ¹²; for four DLFL techniques, we use and enhance the source code from the previous studies to implement them on source code [65, 66]. We also double-checked the implementation and fully tested our code, but there could be errors that we did not notice.

Threats to external validity. Threats to external validity relate to generalizability of our results. We use FL techniques using neural networks (*i.e.*, MLP-FL, CNN-FL, BiLSTM-FL and DeepRL4FL), whose outputs are not stable, meaning that the localization results are not the same through different training times. That drawback is

¹²https://gzoltar.com/

caused by characteristic of deep learning technology. To make the results more reliable, we follow the convention strategy by repeating the experiments ten times and using the average score as the experimental results.

Another threat to external validity is the subject programs used for our experiments. Our subject programs are commonly used in the field of software debugging, which are all from the real-life development. However, the experimental results may not apply to all programs because there are still many unknown and complicated factors in realistic debugging that could affect the experiment results. For example, in our approach, a specific failing test case is needed for the obtain of an influential slice to exclude irrelevant statements for a smaller inspecting scope. However, such a choice strategy is suitable for single-fault scenarios since the chosen failing test case can only reveal its own root cause. Consequently, if there are more than one fault contained in a program, the remaining faults will be ignored, *i.e.*, our approach can be affected by multiple-faults scenarios. Specifically, for multiple faults, we have two typical problems. The one is that dynamic information is partially related to multiple faults, *i.e.*, a failing test case only executes part of all the faulty statements of multiple faults. Dynamic FL approaches including UNITE cannot obtain the dynamic information of unexecuted faulty statements, and thus it is difficult for dynamic approaches to be effective at locating those faulty statements not executed by the failing test case. The other one is that multiple faults have complicated effect (e.g., fault interference and coupling effect [6, 8, 63]), which is still difficult to be accurately analyzed. Dynamic slicing used by our approach UNITE also suffer from this problem, and may miss part of all the faulty statements of multiple faults. Consequently, UNITE is ineffective at locating those faulty statements of multiple faults missed by dynamic slicing. To alleviate the problem, we may leverage clustering technology (e.g., [14]) to alleviate the effect by transforming the context of multiple faults into that of single faults. Thus, it is worthwhile to incrementally extend our study to more applications (e.g., multiple-faults programs) to seek additional insights.

Threats to construct validity. Threats to construct validity relate to the suitability of our evaluation. We adopt the widely used metrics (*i.e., TopN, MAR, MFR* and *RImp*) to evaluate UNITE. According to the extensive use of the measurements, the threat is acceptably mitigated.

6 CONCLUSION AND FUTURE WORK

In this paper, we propose UNITE: an influential co<u>N</u>text-Gu<u>I</u>ded <u>T</u>race r<u>E</u>presentation, to represent the trace from both global and local contexts with influential semantics for effective FL. UNITE embodies two key ideas: (1) not only local context but also global context is useful for FL trace representation. (2) program dependencies are potential for upgrading 'occurrence' semantics. To implement the two key ideas UNITE uses the widely-used weighting capability of information retrieval to combine global and local contexts, and further leverages program slicing to incorporate influence semantics into the trace representation through program dependencies. We apply UNITE to 12 state-of-the-art FL techniques and conduct large-scale experiments on 20 benchmark programs. The results show that UNITE significantly improves 12 FL techniques, *e.g.*, the average relative improvement for the most important Top-N metric [17], *i.e.*, Top-1, Top-3, Top-5 and Top-10, achieves 35.58%, 119.90%, 47.43% and 50.66%, respectively.

In the future, we plan to design sophisticated weighting functions for a further optimization on global and local contexts. We also plan to compose influence semantics with other solutions proposed in the literature to improve FL effectiveness (*e.g.*, feature selection).

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